

RUMD.org: A molecular dynamics code optimized for GPUs

Roskilde University Molecular Dynamics

Thomas Schröder,
Glass & Time, NSM, RUC

GPU Computing Today and Tomorrow
GPU-Lab, DTU, 18/8-2011



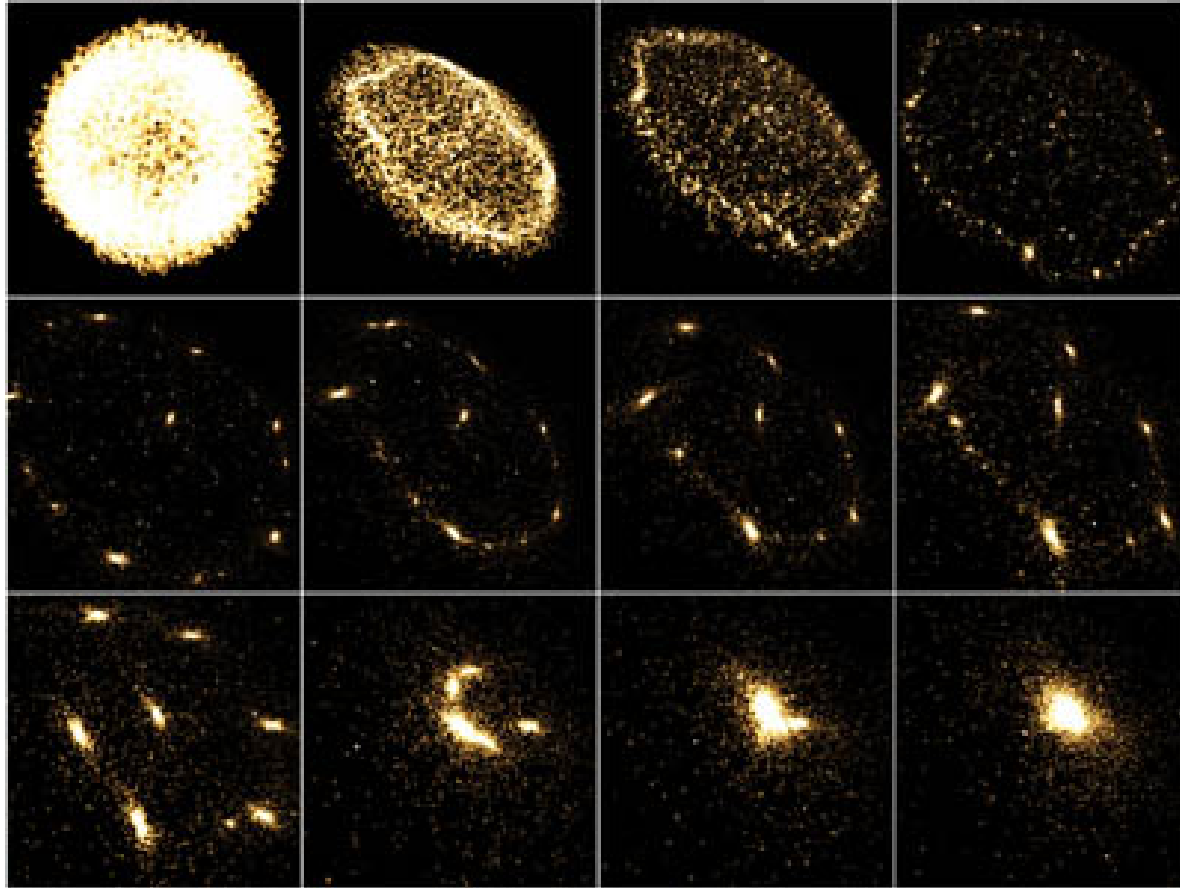
Glass and Time



Danish National Research Foundation Centre for Viscous Liquid Dynamics

The Nbody program:

Simulating galaxies interacting by gravitational forces



$$\mathbf{f}_{ij} = G \frac{m_i m_j}{\|\mathbf{r}_{ij}\|^2} \cdot \frac{\mathbf{r}_{ij}}{\|\mathbf{r}_{ij}\|},$$

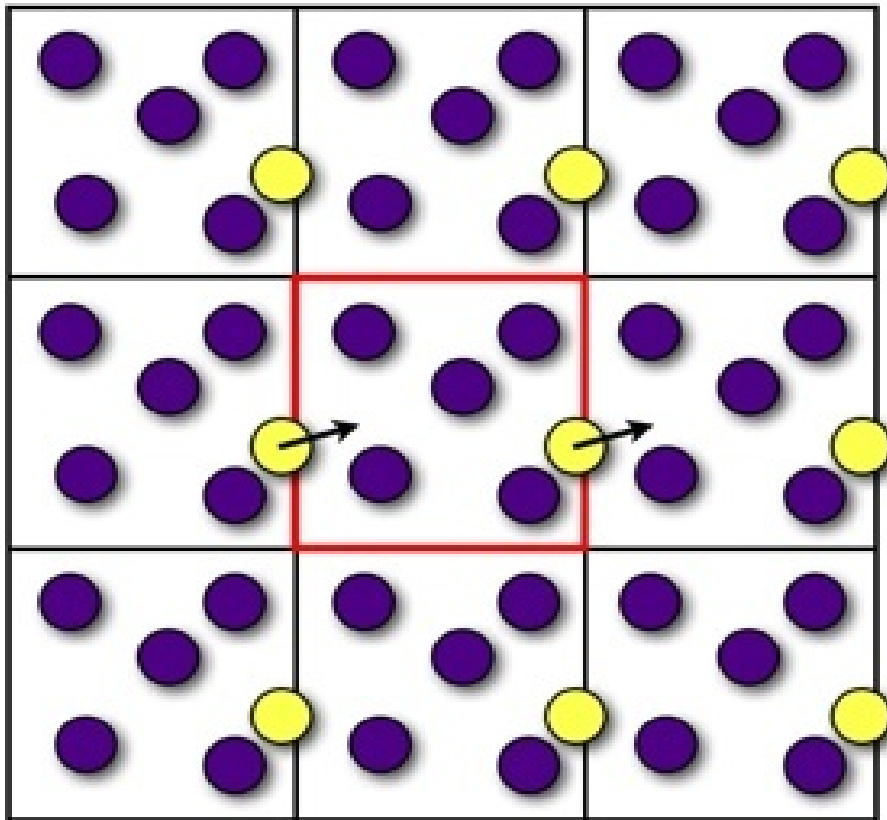
$$\mathbf{F}_i = \sum_{\substack{1 \leq j \leq N \\ j \neq i}} \mathbf{f}_{ij} = G m_i \cdot \sum_{\substack{1 \leq j \leq N \\ j \neq i}} \frac{m_j \mathbf{r}_{ij}}{\|\mathbf{r}_{ij}\|^3}.$$

- 1) Calculate forces and accelerations, $O(N^2)$
- 2) Advance positions and velocities one timestep using Newton's equations $O(N)$.
- 3) Goto 1

Molecular Dynamics (MD)

Like Nbody, except:

Periodic boundary conditions



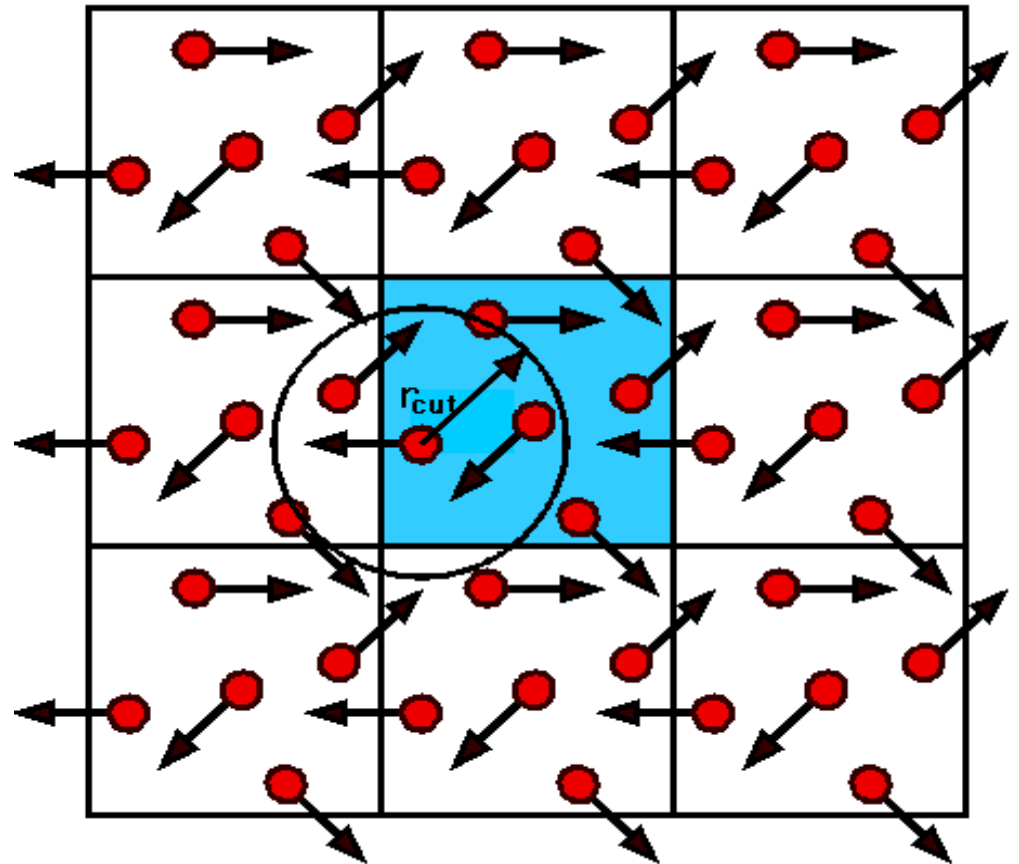
Simulations are 3D

Particles inside cut-off: ~ 100

Lennard-Jones pair potential:

$$\Phi_{\alpha\beta}(r) = 4\epsilon_{\alpha\beta} \left(\left(\frac{\sigma_{\alpha\beta}}{r} \right)^{12} - \left(\frac{\sigma_{\alpha\beta}}{r} \right)^6 \right)$$

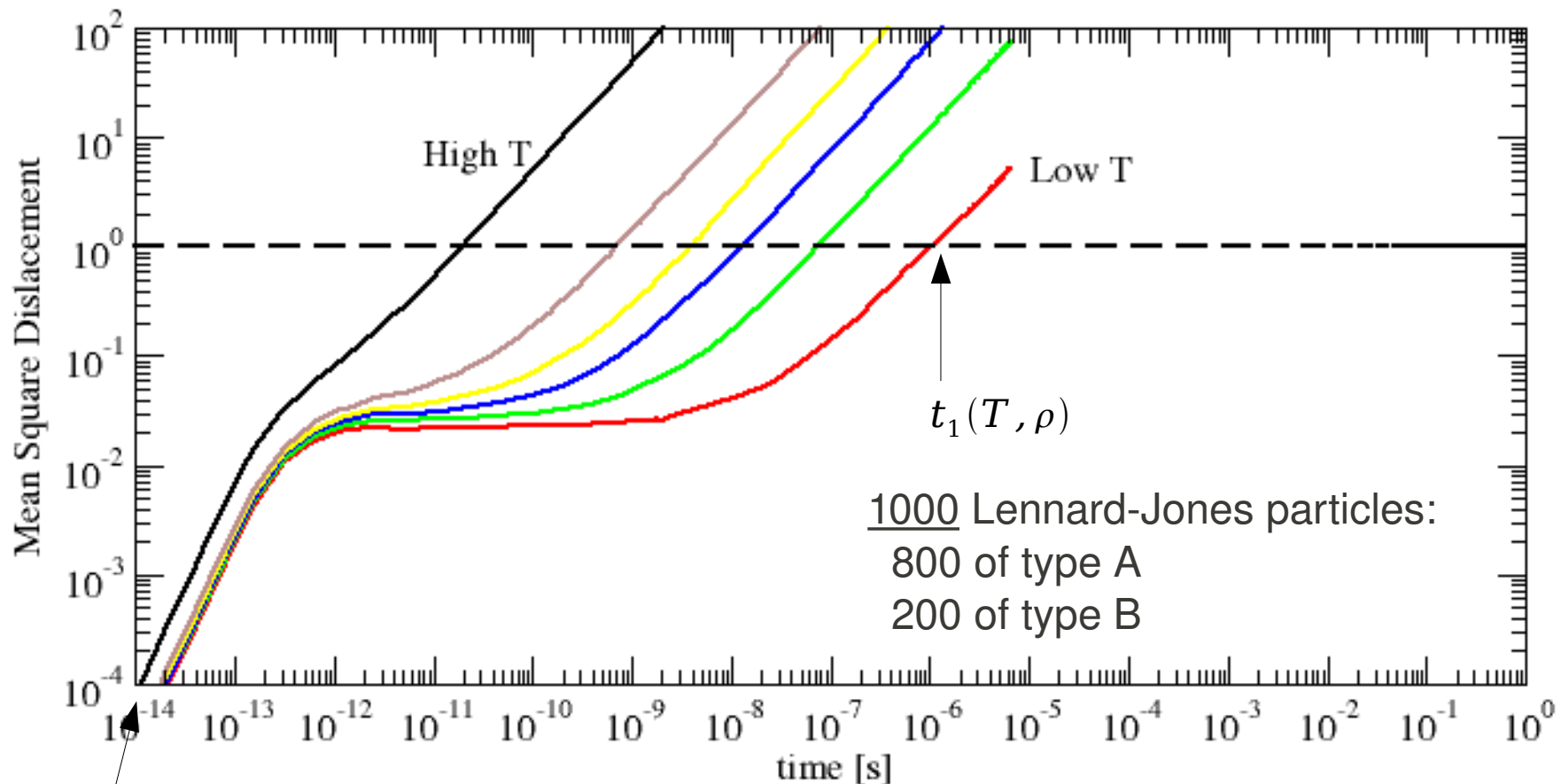
Cut-off in potential (nb-lists) and
minimal image convention



Nbody: $O(N^2)$, regular, static
MD: $O(N)$, irregular, dynamic

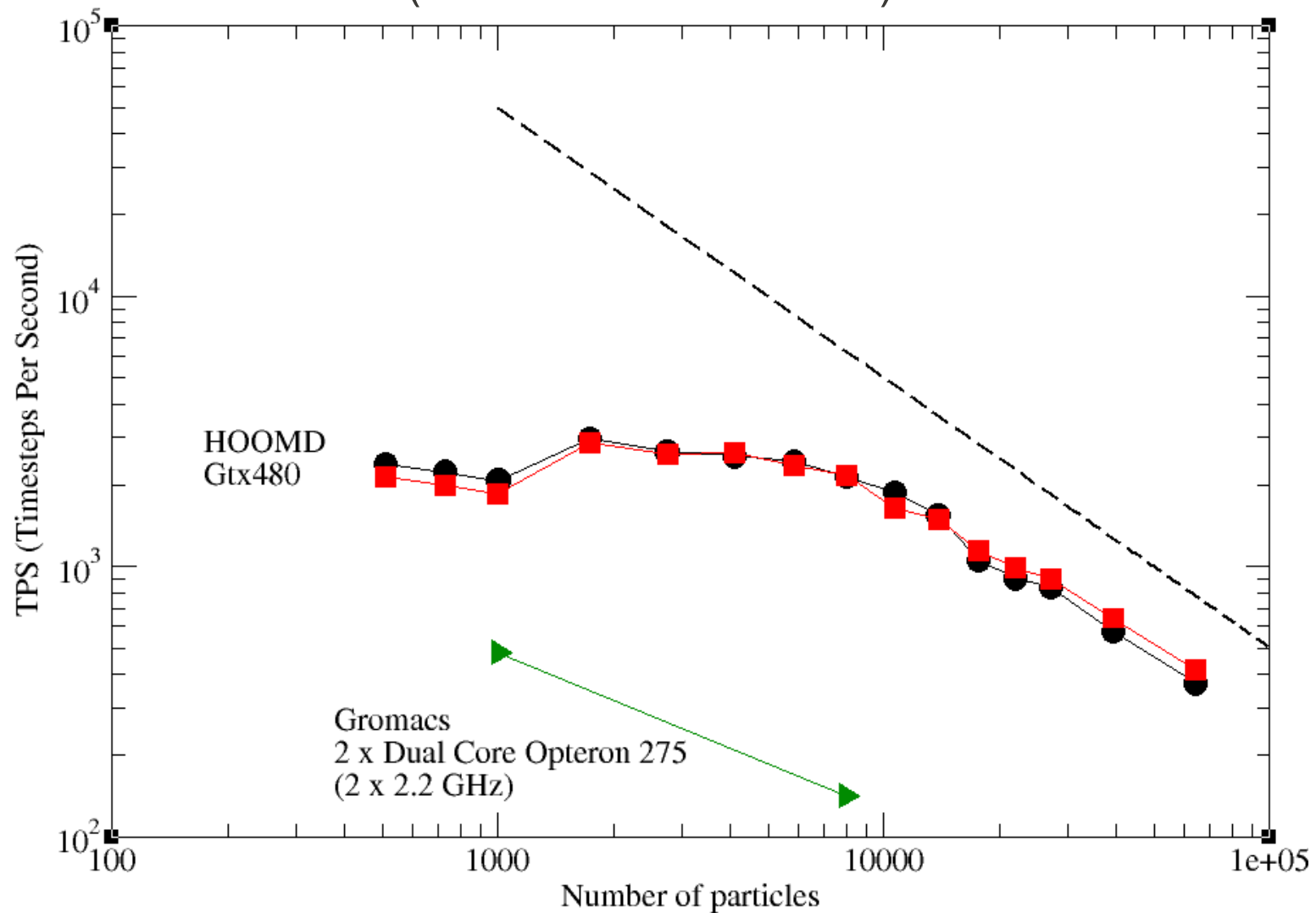
The need for speed:

To test theories and investigate new phenomena, we want to simulate liquids on the millisecond timescale and beyond.



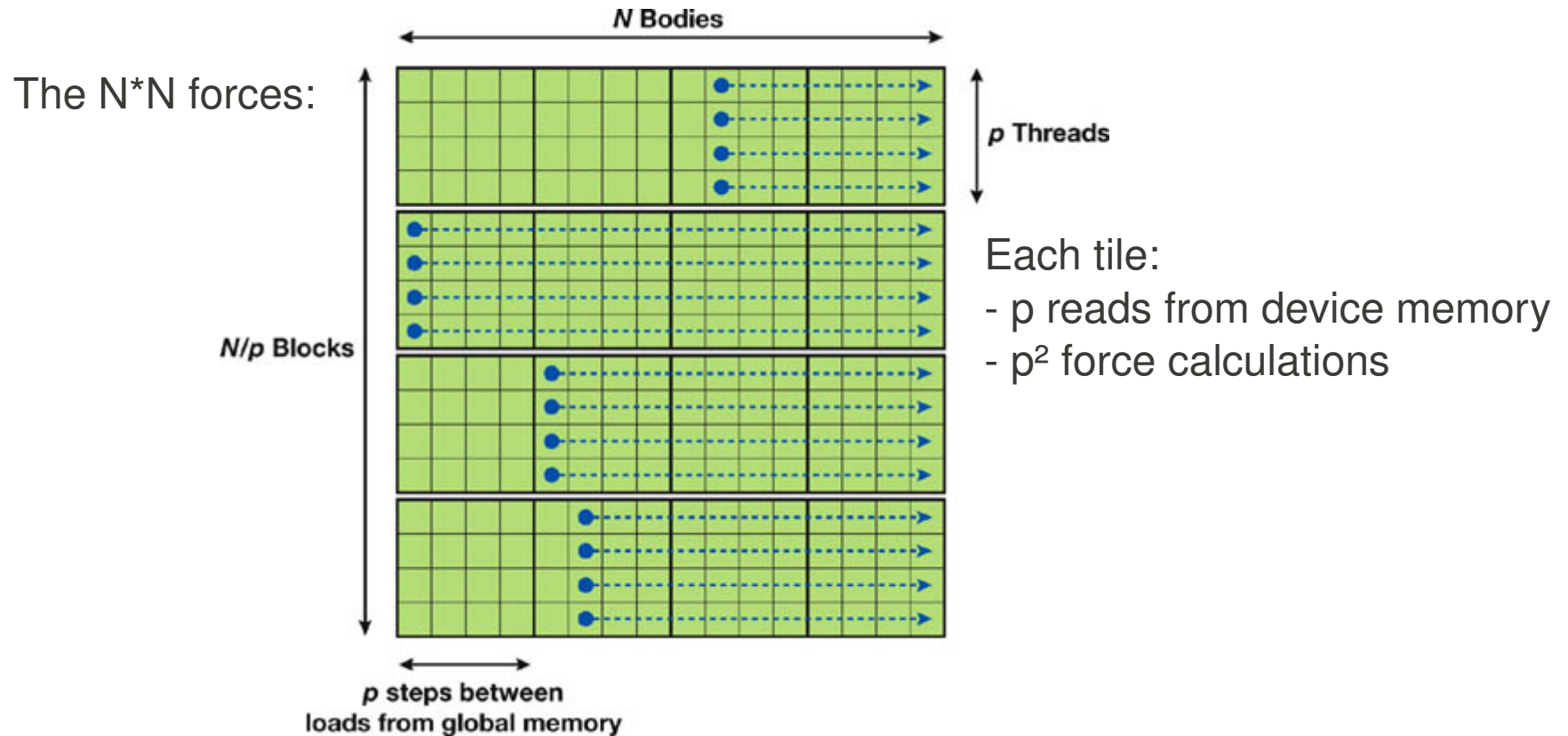
Size of our time-step

CPU versus GPU (4 versus 480 cores)

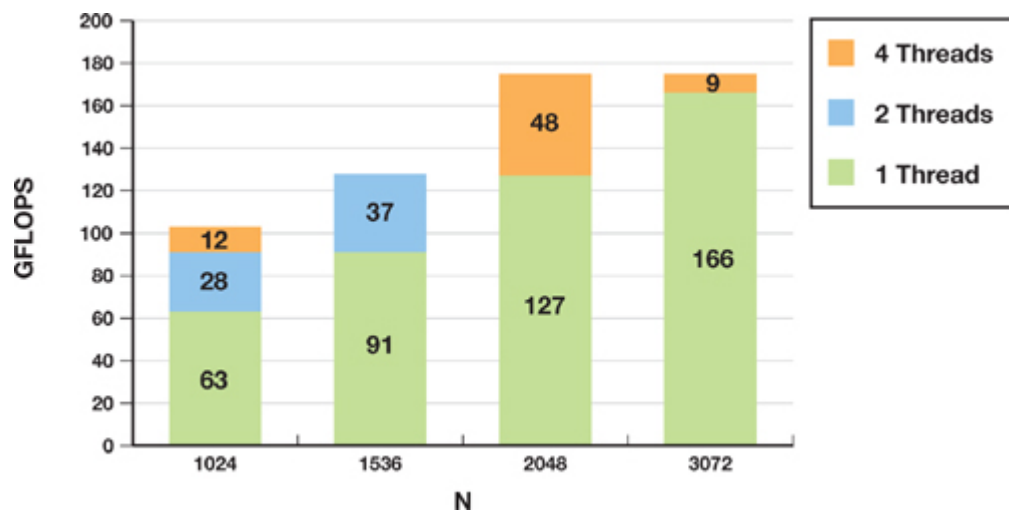
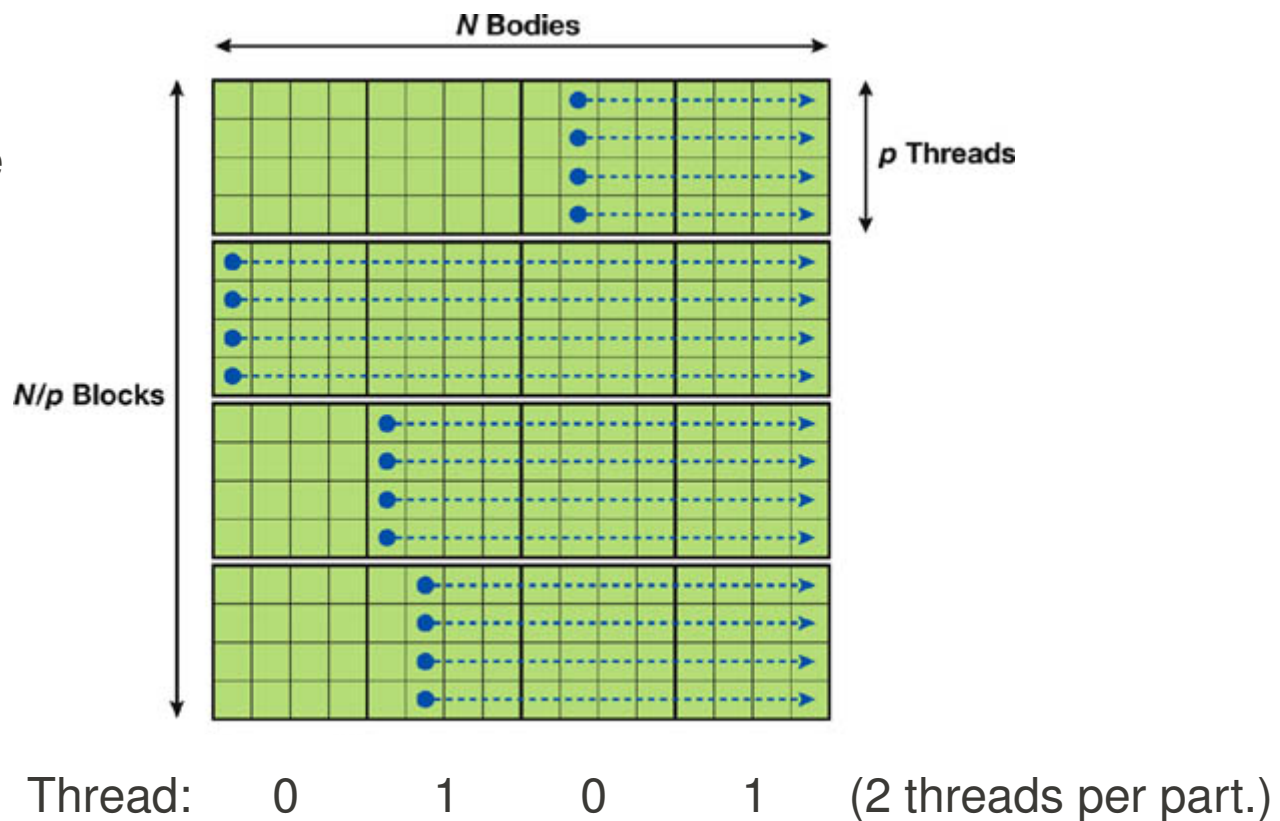


Challenge: Getting good speed-up when samples are small ($N \sim 1000$)

The overall structure of force calculations in Nbody (and RUMD):



Optimizing for small samples:
Using several threads per particle
-> better latency hiding



Strategy for RUMD implementation:

- Optimize for $N=1000$

- Worry about good scaling later

First step:

- Re-implementing Nbody [$O(N^2)$].

- 4 times faster than highly optimized CPU MD program [$O(N)$], for $N=1000$!!!!

Second step:

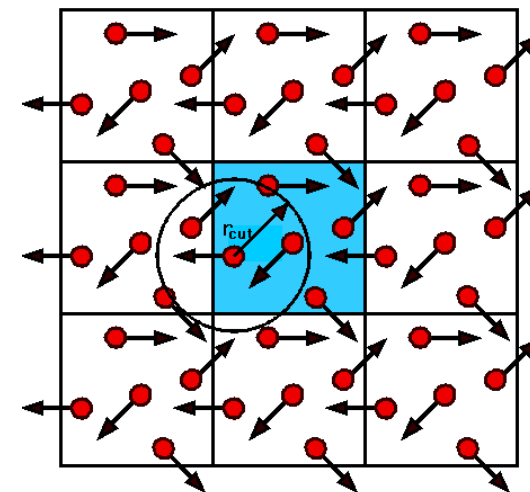
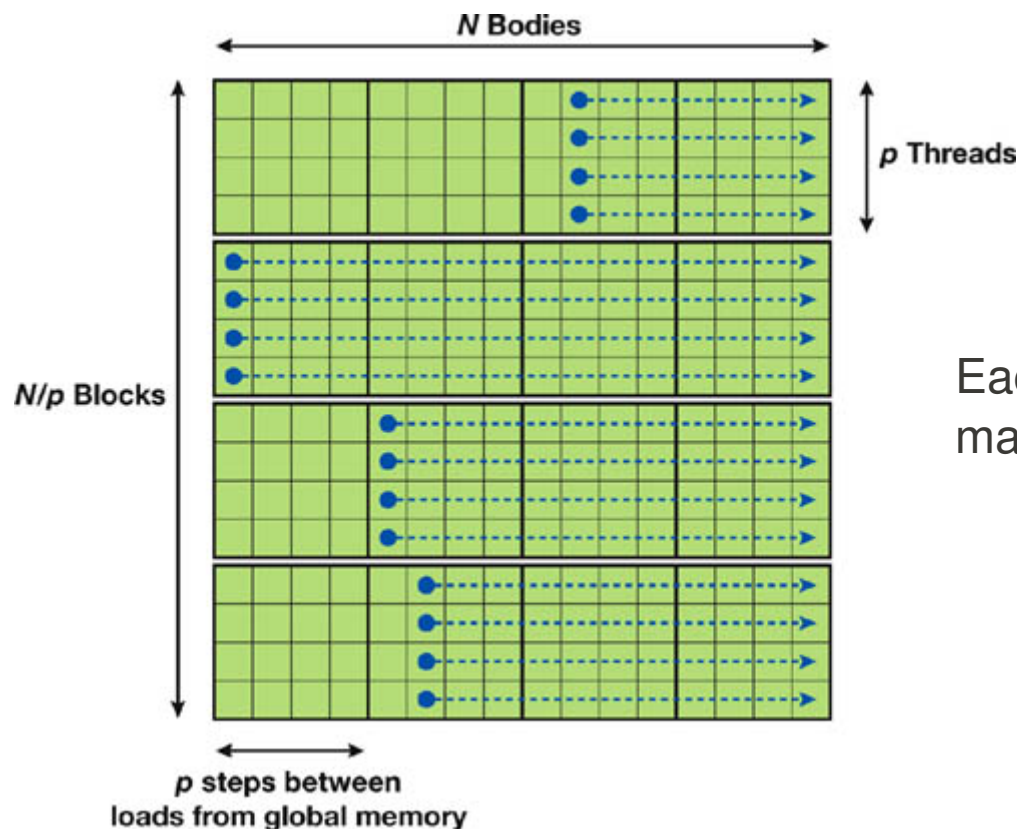
- Changing interactions to multi-component Lennard-Jones

- (+ other molecular dynamics features)

- 2 times faster than highly optimized CPU MD program [$O(N)$], for $N=1000$

Third step: Adding 'Neighbour-lists'
 - making force calculation $O(N)$ instead of $O(N^2)$

Actually neighbour-matrix:



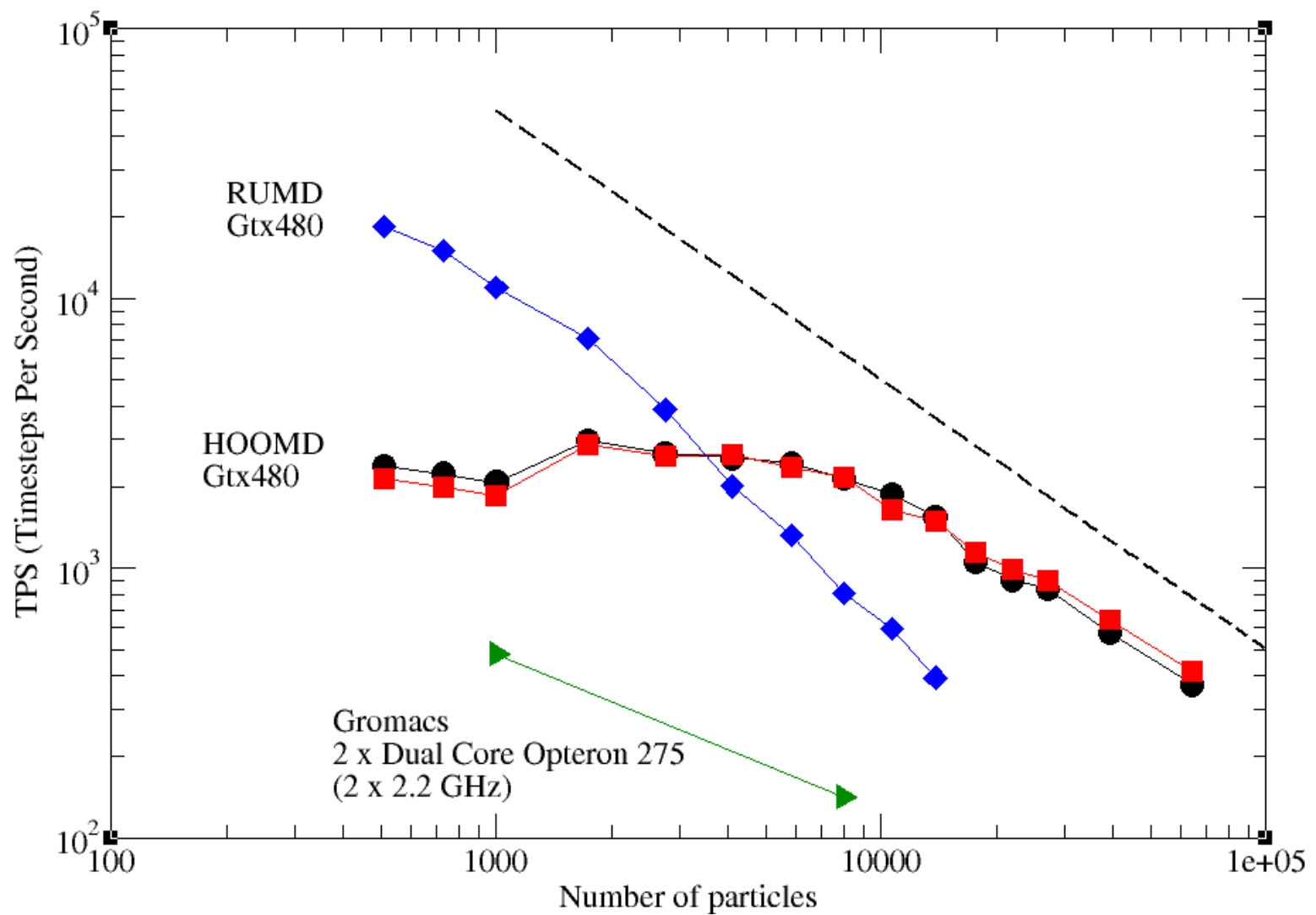
Each tile has a (sub-) Neighbour-matrix, encoded as (32 bit) integers:

```
0010 ...
0101
1000
1001
.
.
.
```

Neighbour matrix decoded by:

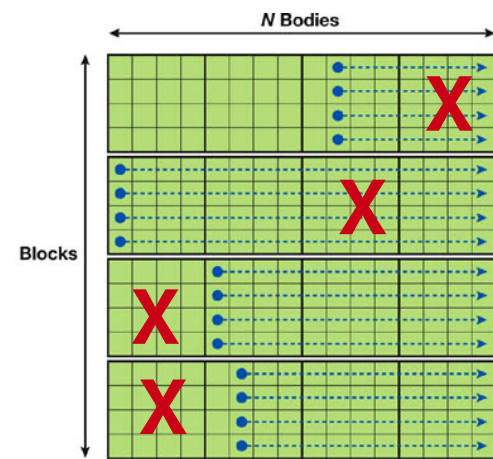
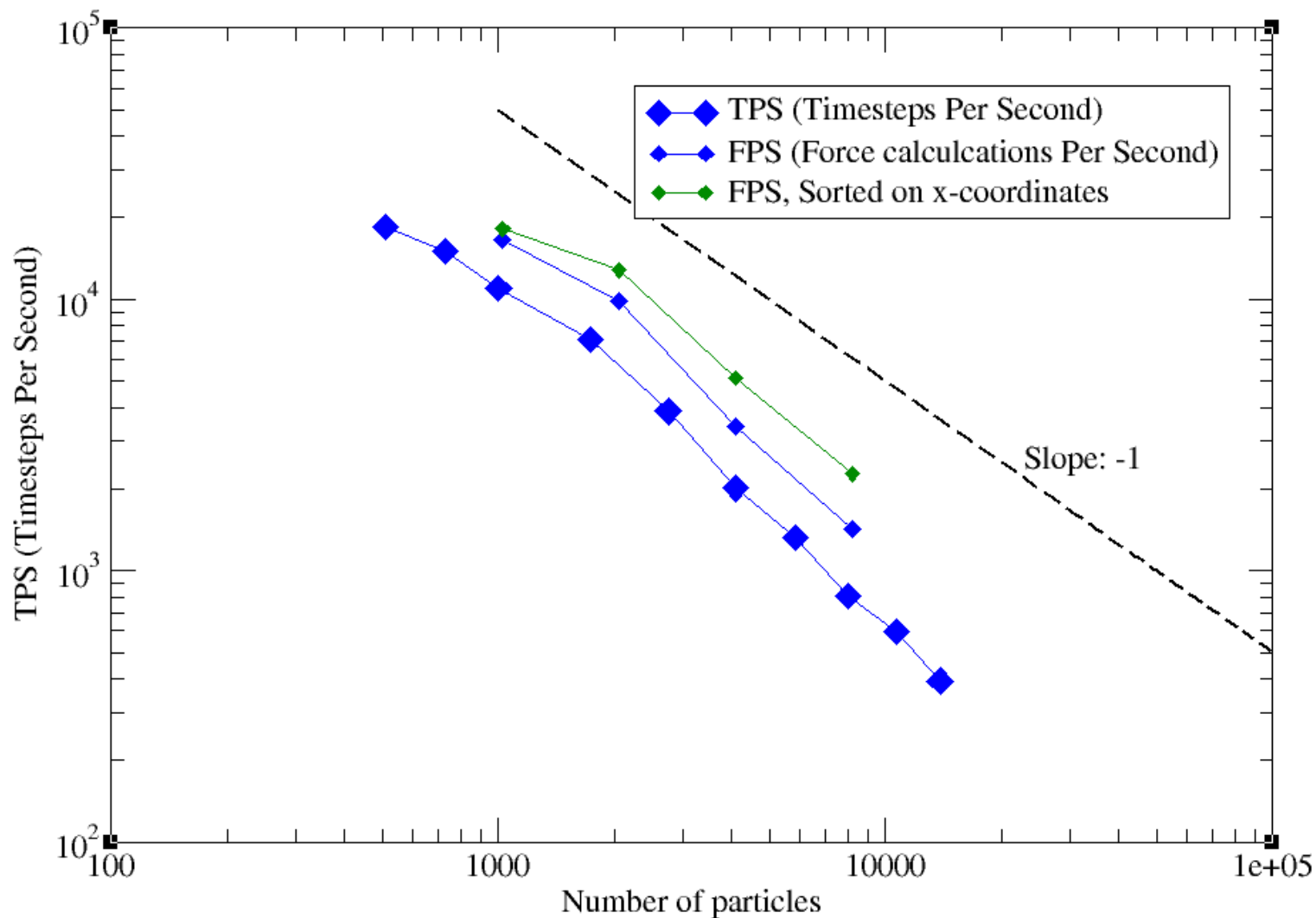
`__ffs(x)` returns the position of the first (least significant) bit set in integer parameter **x**. The least significant bit is position 1. If **x** is 0, `__ffs()` returns 0.

Benchmarks



For $N=1000$ RUMD 23 times faster than Gromacs (4 opteron cores)
5 times faster than HOOMD (same Gtx480)

Improving scaling by sorting in 3D space (experimental)



Each block has a list of which other blocks it interacts with

Plus a number of other features (see <http://rumd.org>):

- van der Waals type pair potentials: Lennard-Jones, Gaussian core, Inverse Power Law, and more. It is easy to implement new pair potentials.
- Bond stretching potentials: Harmonic and FENE
- Multicomponent simulations
- NVE and NVT ensemble simulations
- python interface ←
- Post simulation analysis tools

```
import sys
sys.path.insert(0, "../Swig")

from rumdSimulation import rumdSimulation, rumd

# Setup simulation with initial configuration
sim = rumdSimulation("start.xyz.gz")

# Choose integrator
itg = rumd.IntegratorNVT(timeStep=0.002, targetTemperature=0.5)
#itg = rumd.IntegratorNVE(timeStep=0.0025)
sim.SetIntegrator(itg)

# Create Lennard-Jones pair-potential
potential = rumd.Pot_LJ_12_6()

# Set up parameters for Lennard-Jones interactions ( Kob & Andersen )
# i j Sig Eps Rcut (in units of Sigma_ij)
potential.SetParams(0, 0, 1.00, 1.00, 2.5)
potential.SetParams(0, 1, 0.80, 1.50, 2.5)
potential.SetParams(1, 0, 0.80, 1.50, 2.5)
potential.SetParams(1, 1, 0.88, 0.50, 2.5)
sim.SetPotential(potential)

sim.Run(30000000)

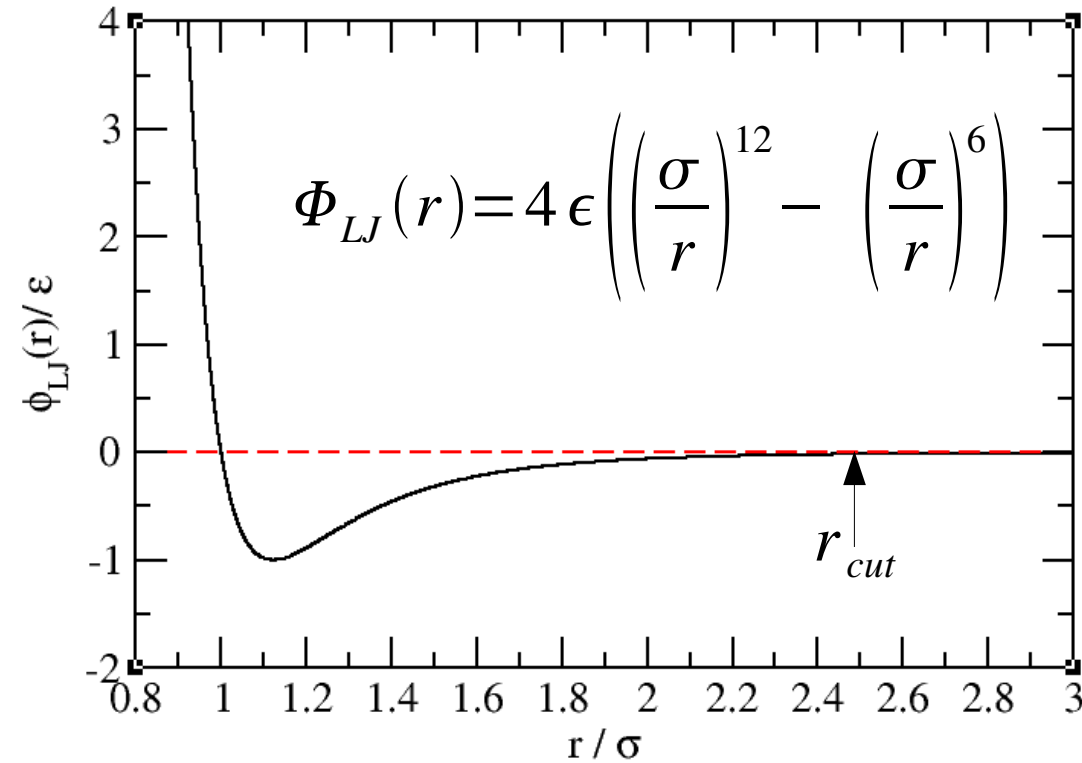
# Save the final configuration
sim.sample.WriteConf("end.xyz.gz")
```

The RUMD developers:

Nicholas Bailey,
Trond Ingebrigtsen,
Jesper S. Hansen,
Lasse Bøhling,
Heine Larsen,
Thomas Schröder

Thank you for your attention

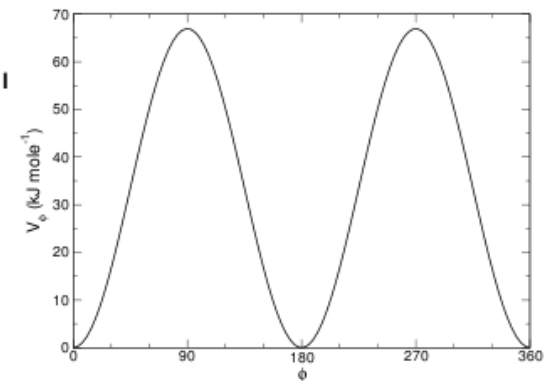
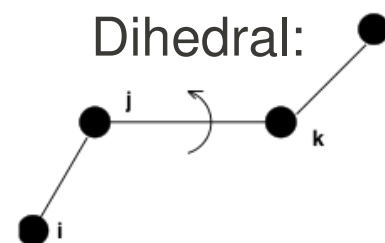
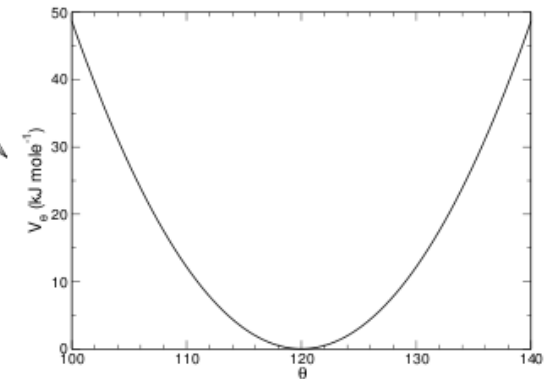
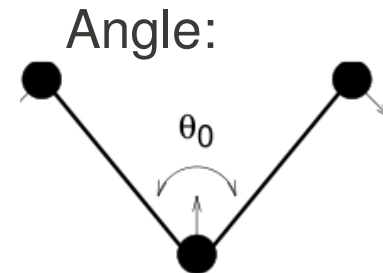
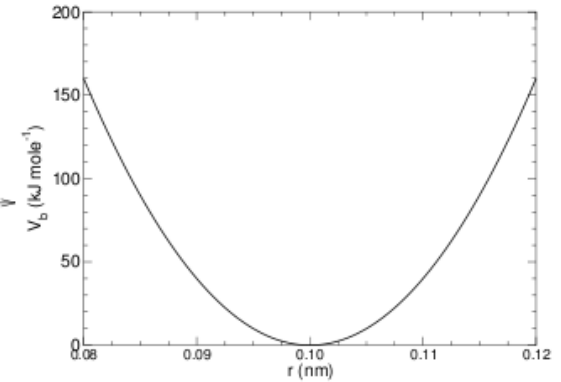
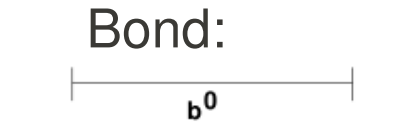
The Lennard-Jones potential:

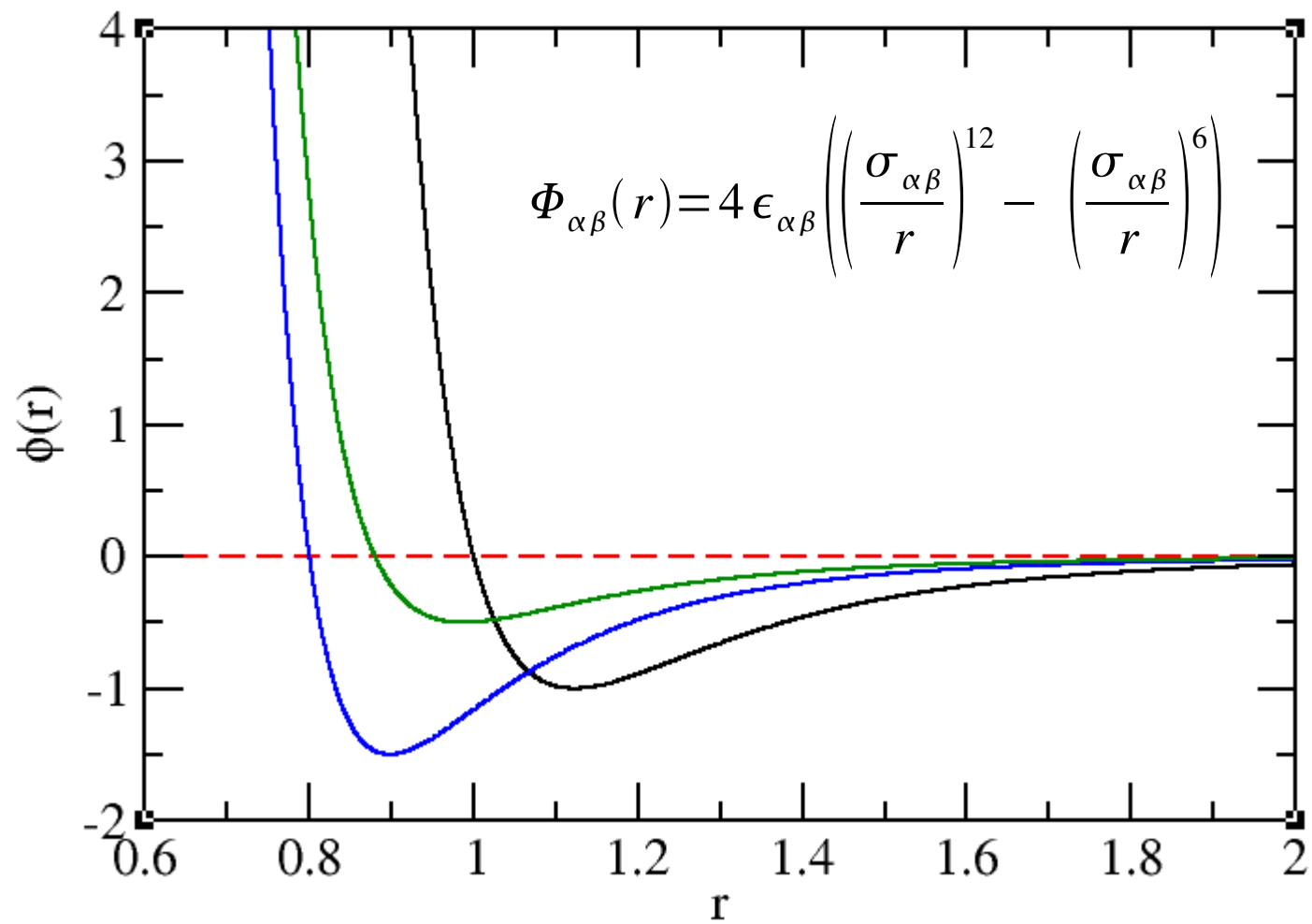


Other non-bonded pair-interactions:

- Coulomb
- Soft spheres: $\phi(r) \propto r^{-n}$
- ...
- ...
- ...

Bonded interactions:

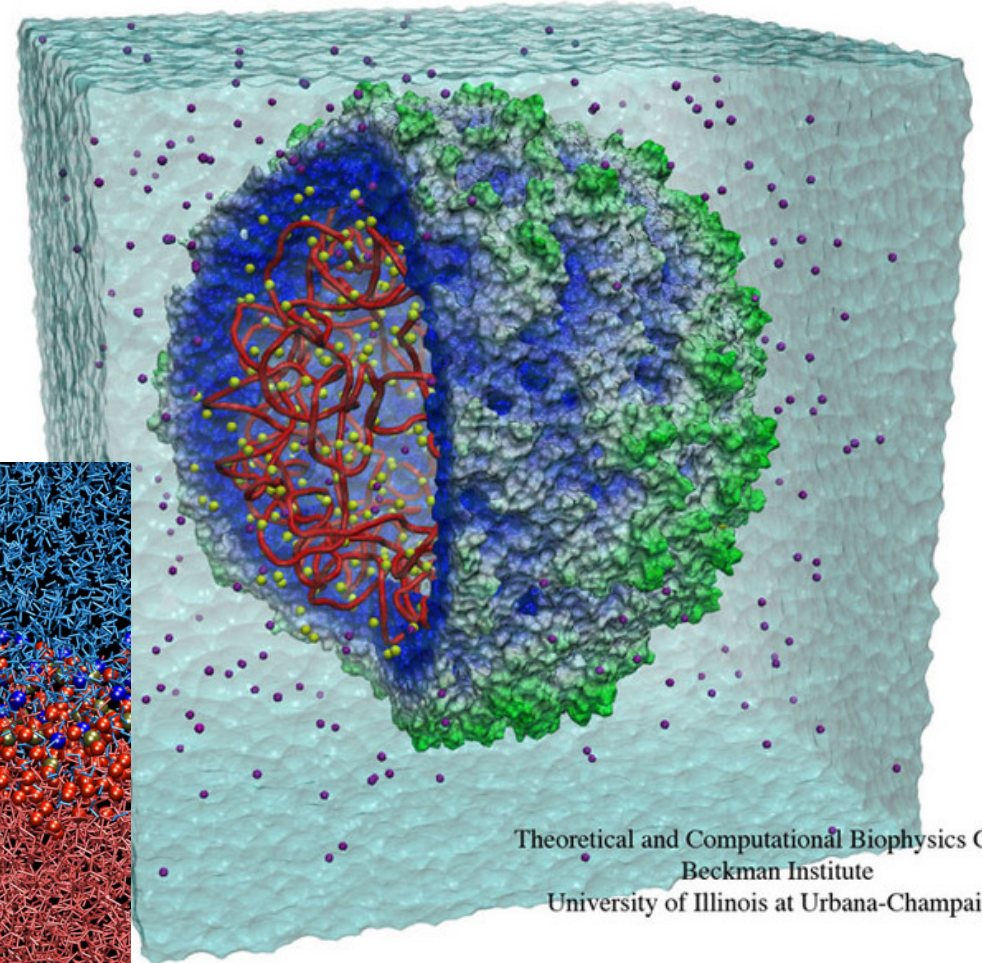
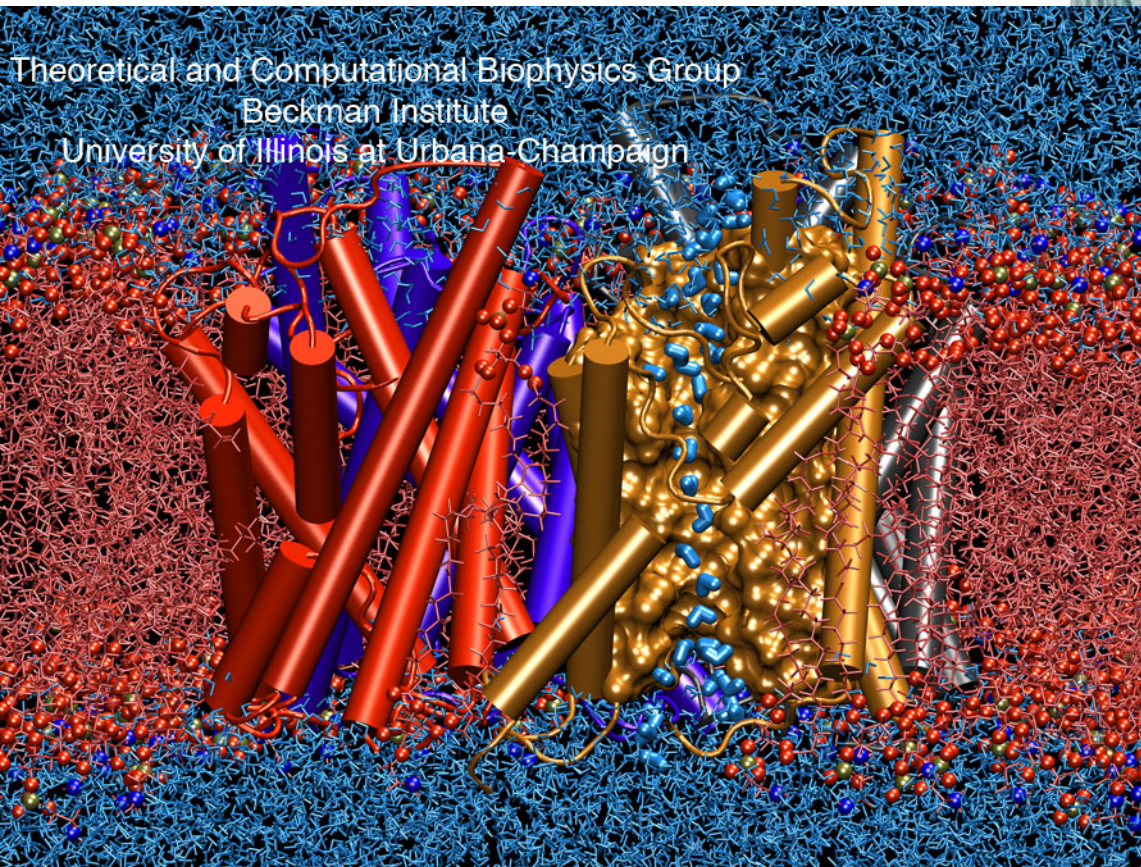




From these building blocks very complex molecules can be simulated:

satellite tobacco mosaic virus, complete with protein, RNA, ions, and a small water box

Water permeation through
membrane water channels



[<http://www.ks.uiuc.edu/Gallery/>]

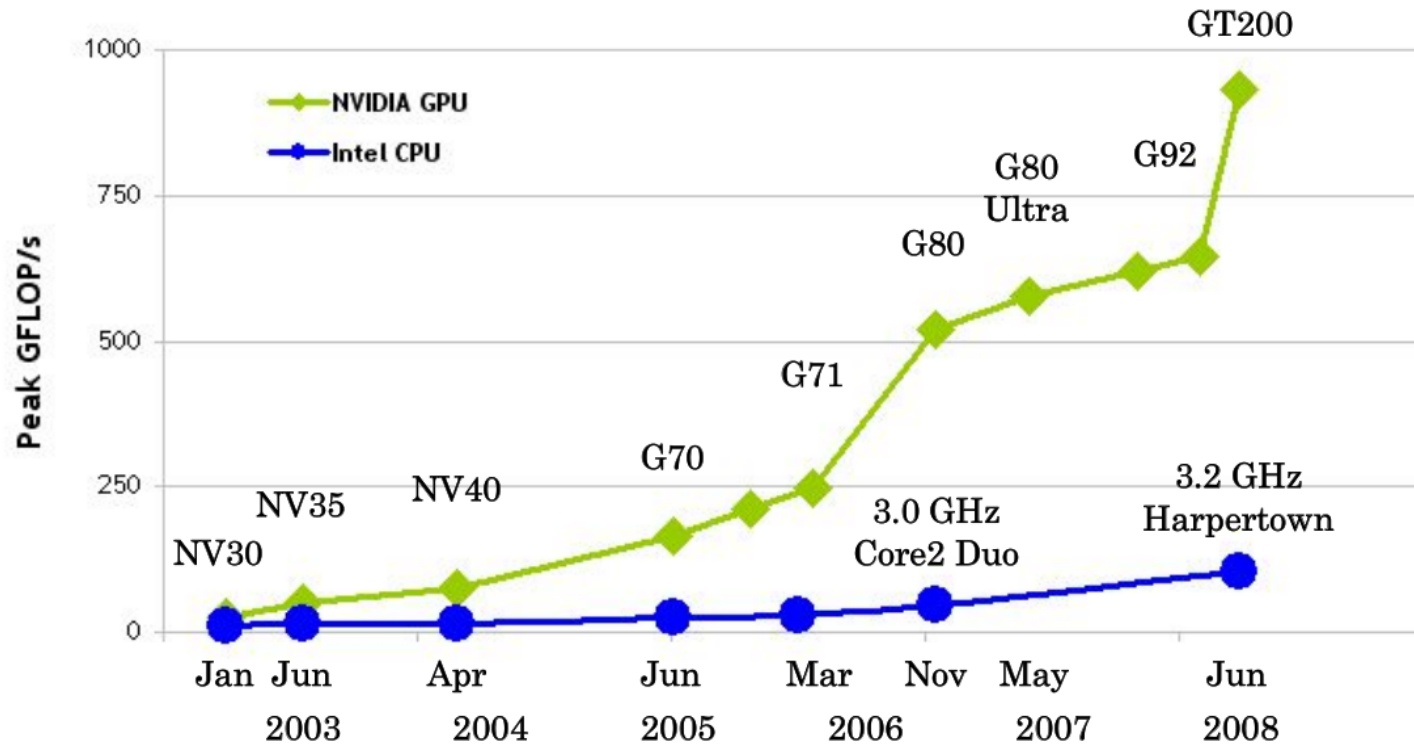
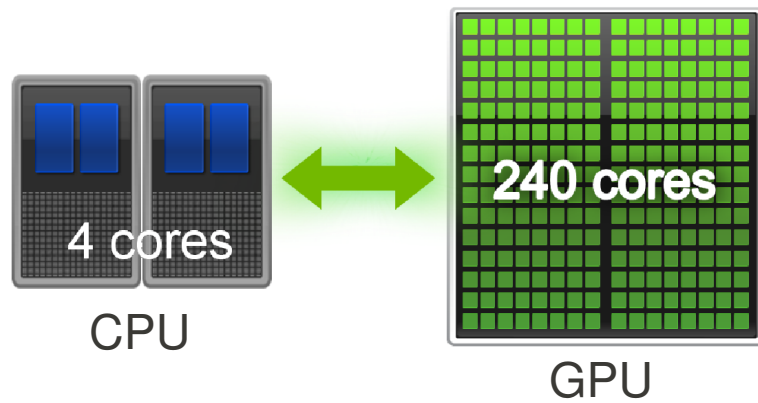
The Glass and Time GPU Cluster



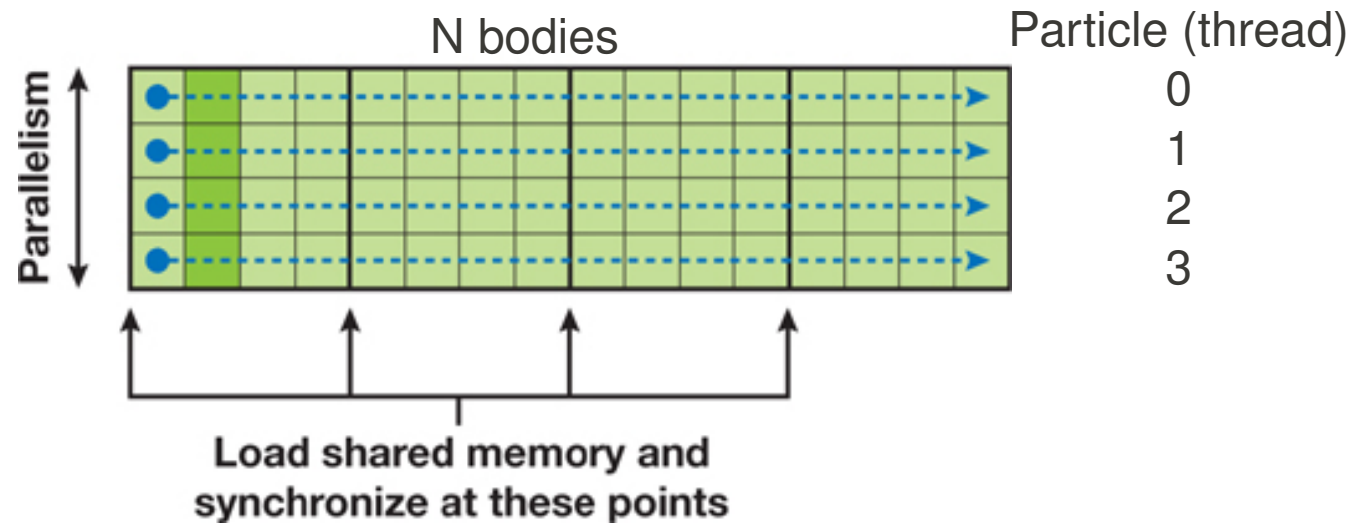
92 GPU's (mostly Gtx280)

Total theoretical peak performance: ~ 80 TFlops

CPU vs. GPU



The new Glass & Time cluster: 92 GPU's (GT200). Total peak performance: 85.8 TFlops.



```

01.  __global__ void
02.  calculate_forces(void *devX, void *devA)
03.  {
04.      extern __shared__ float4[] shPosition;
05.      float4 *globalX = (float4 *)devX;
06.      float4 *globalA = (float4 *)devA;
07.      float4 myPosition;
08.      int i, tile;
09.      float3 acc = {0.0f, 0.0f, 0.0f};
10.      int gtid = blockIdx.x * blockDim.x + threadIdx.x;
11.      myPosition = globalX[gtid];
12.      for (i = 0, tile = 0; i < N; i += p, tile++) { ← Loop over tiles
13.          int idx = tile * blockDim.x + threadIdx.x;
14.          shPosition[threadIdx.x] = globalX[idx]; ← Read to shared memory
15.          __syncthreads();
16.          acc = tile_calculation(myPosition, acc); ← Do 'my' part of tile
17.          __syncthreads();
18.      }
19.      // Save the result in global memory for the integration step.
20.      float4 acc4 = {acc.x, acc.y, acc.z, 0.0f};
21.      globalA[gtid] = acc4;
22.  }

```

```

01.  __device__ float3
02.  tile_calculation(float4 myPosition, float3 accel)
03.  {
04.      int i;
05.      extern __shared__ float4[] shPosition;
06.      for (i = 0; i < blockDim.x; i++) {
07.          accel = bodyBodyInteraction(myPosition, shPosition[i], accel);
08.      }
09.      return accel;
10.  }

```

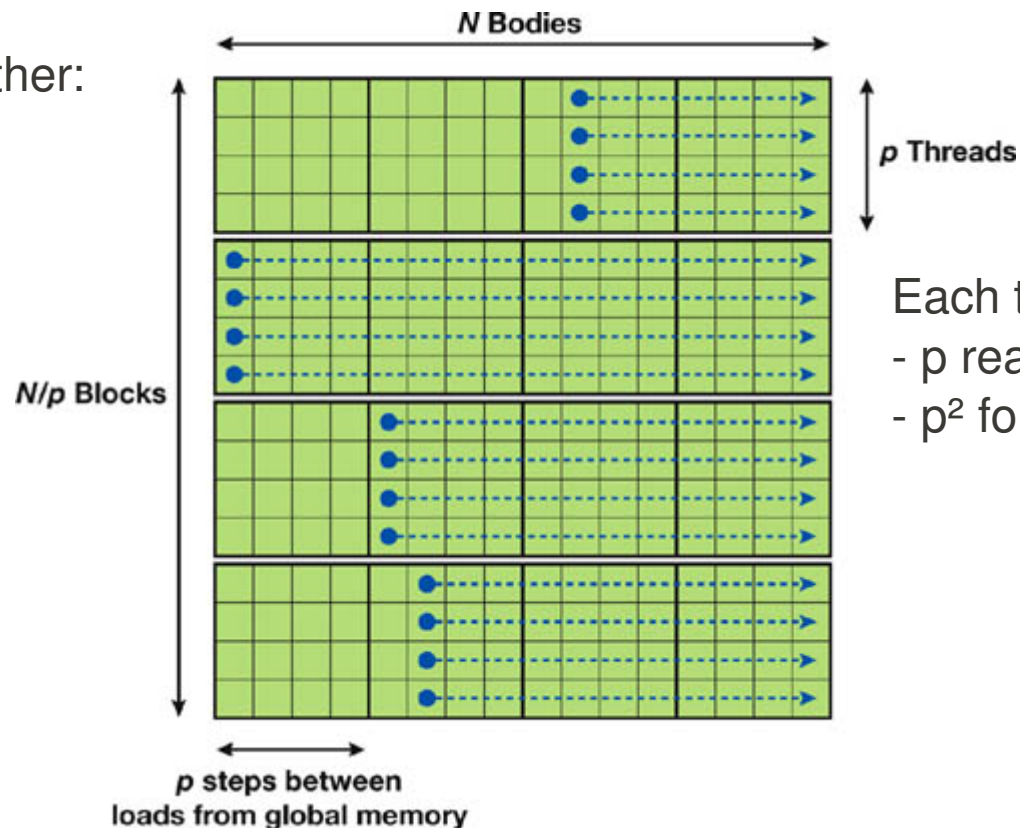
```

01.  __device__ float3
02.  bodyBodyInteraction(float4 bi, float4 bj, float3 ai)
03.  {
04.      float3 r;
05.      // r_ij [3 FLOPS]
06.      r.x = bj.x - bi.x;
07.      r.y = bj.y - bi.y;
08.      r.z = bj.z - bi.z;
09.      // distSqr = dot(r_ij, r_ij) + EPS^2 [6 FLOPS]
10.      float distSqr = r.x * r.x + r.y * r.y + r.z * r.z + EPS2;
11.      // invDistCube = 1/distSqr^(3/2) [4 FLOPS (2 mul, 1 sqrt, 1 inv)]
12.      float distSixth = distSqr * distSqr * distSqr;
13.      float invDistCube = 1.0f/sqrtf(distSixth);
14.      // s = m_j * invDistCube [1 FLOP]
15.      float s = bj.w * invDistCube;
16.      // a_i = a_i + s * r_ij [6 FLOPS]
17.      ai.x += r.x * s;
18.      ai.y += r.y * s;
19.      ai.z += r.z * s;
20.      return ai;
21.  }

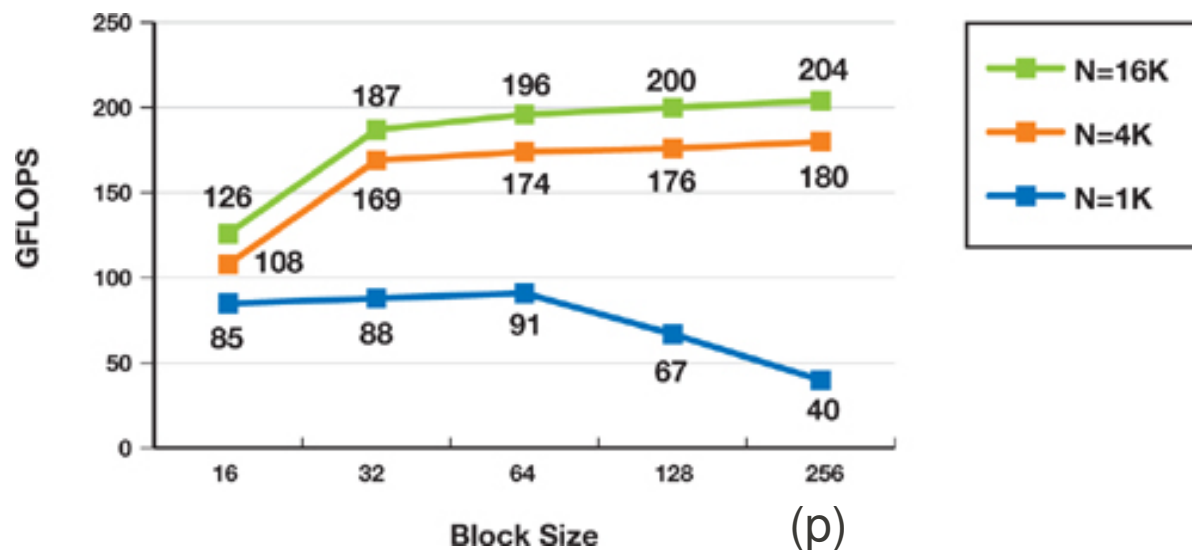
```

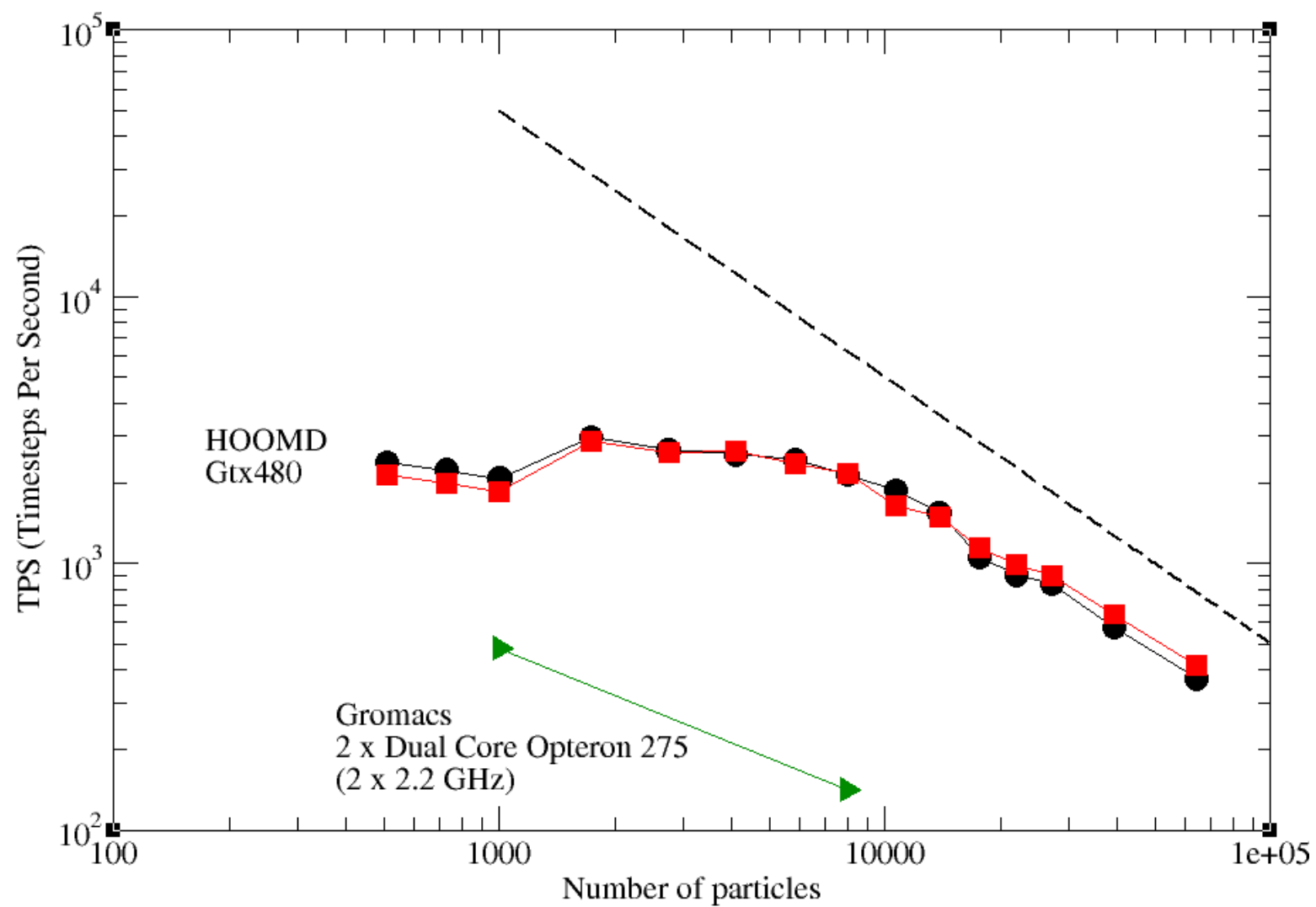
$$\mathbf{f}_{ij} = G \frac{m_i m_j}{\|\mathbf{r}_{ij}\|^2} \cdot \frac{\mathbf{r}_{ij}}{\|\mathbf{r}_{ij}\|},$$

Putting it all together:



Full speed (GTX 8800):
~ 200GFlops





Corresponding kernel in RUMD:

```
template<int STR, int CONFT, class P, class S>
__device__ __host__ float4 fij( P* Pot, float4 my_r, float4 rj, float4* my_f, float4* my_w,
float4* my_sts, float4* my_misc, float* param, S* simBox, float* simBoxPointer ){

    float4 dist = simBox->calculateDistance(my_r, rj, simBoxPointer);  ← Periodic Boundary Conditions
                                                                    (prepared for other shaped boxes)

    // Inside cut-off for interaction? (param[0]=Rcut^2)
    if ( dist.w <= param[0] && dist.w >= 0.000001f ){  ← Cut-off
        float s;

        if(CONFT){
            s = Pot->ComputeInteraction(dist.w, param, my_f, my_w, my_misc);
        }
        else{
            s = Pot->ComputeInteraction(dist.w, param, my_f, my_w);  ← Easy to add other potentials
        }

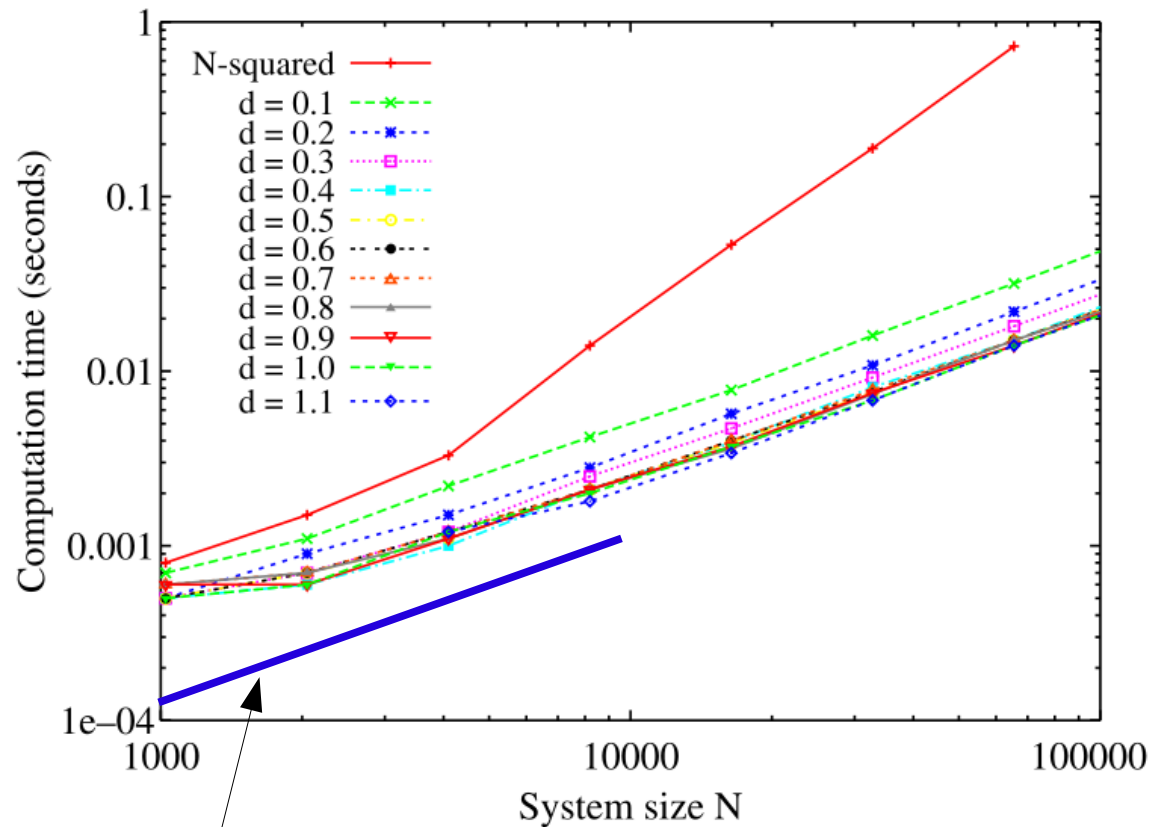
        (*my_f).x += dist.x * s;
        (*my_f).y += dist.y * s;
        (*my_f).z += dist.z * s;

        if(STR){  ← Templates controlling what gets calculated
            // stress - diagonal components
            (*my_sts).x -= dist.x * dist.x * s;  // xx
            (*my_sts).y -= dist.y * dist.y * s;  // yy
            (*my_sts).z -= dist.z * dist.z * s;  // zz
            // stress - off-diagonal components
            (*my_sts).w -= dist.y * dist.z * s;  // yz
            (*my_w).y -= dist.x * dist.z * s;    // xz
            (*my_w).z -= dist.x * dist.y * s;    // xy
        }
    } // END  dist.w <= param[0]...

    return dist.w;
}
```

Compared to the competition:

“Harvesting graphics power for MD simulations”,
van Meel et al., Molecular Simulation, (2008):



Our program: Optimized for small N .

Speed-up compared to optimized CPU programs: ~ 20